

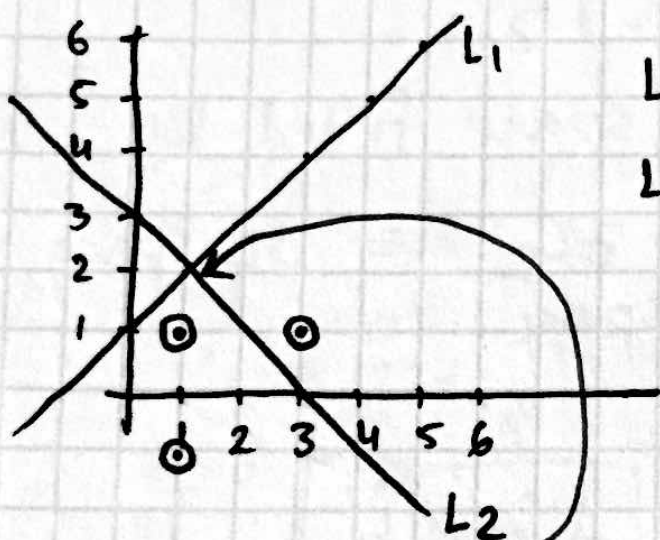
② Simultaneous Eqⁿ:

$$\left. \begin{aligned} a_1x + b_1y &= c_1 \\ a_2x + b_2y &= c_2 \end{aligned} \right\} \begin{bmatrix} a_1 & b_1 \\ a_2 & b_2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}$$

Matrix form.

$$A\hat{x} = \hat{b}$$

③ Geometric view



$$L_1 \equiv y = 1 \cdot x + 1$$

$$L_2 \equiv y = -1 \cdot x + 3$$

$$x + y = 3$$

$$-x + y = 1$$

$$\begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$$

Combine $\begin{bmatrix} 1 \\ -1 \end{bmatrix}$ and $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$ with weights $\begin{bmatrix} 3 \\ 1 \end{bmatrix}$ to form

$$\text{weights} = \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

③ Col. and Row view:

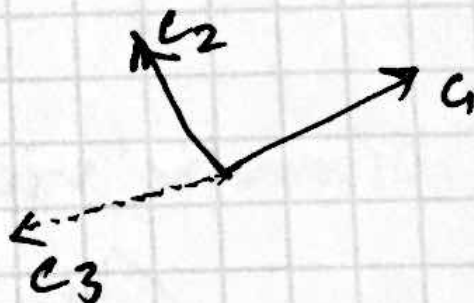
$$\begin{bmatrix} c_1 \\ c_2 \end{bmatrix} x + \begin{bmatrix} c_2 \\ c_1 \end{bmatrix} y = \begin{bmatrix} c_1 & c_2 \\ c_1 & c_2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

or

$$\begin{bmatrix} x & y \end{bmatrix} \begin{bmatrix} -r_1- \\ -r_2- \end{bmatrix} = x \begin{bmatrix} -r_1- \\ -r_2- \end{bmatrix} + y \begin{bmatrix} -r_2- \end{bmatrix}$$

③ Col. & Row space

$$A = \begin{bmatrix} | & | & | \\ C_1 & C_2 & C_3 \\ | & | & | \end{bmatrix}$$



Col space = Entire space filled by

$x C_1 + y C_2 + z C_3 \equiv 3D \text{ space}$
Similarly row space.

③ Popular form : $A \hat{x} = \hat{b}$

col. of A combined by vectors of x to produce \hat{b}

⑤ Solve $Ax = b$

Gaussian Elimination is
convert A to U (upper triang.
matrix).

⑥ Subtracting rows can be expressed
as permutation matrix

$$I = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \text{do nothing}$$

$$E_{2-1} = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \text{subtract row 1} \\ \text{from row 2}$$

$$\therefore E_{2-1} \cdot A \equiv \text{one variable}$$

$$E_{3-1} \cdot E_{2-1} \cdot A \equiv \text{two variables eliminated}$$

$$\textcircled{5} \quad Ax = b \quad \therefore x = \underbrace{A^{-1}}_{\text{inverse.}}$$

means

Permutation performed earlier just needs to be reversed in sign

$$E_{2-1}^{-1} = \text{just change sign of element } \langle 2, 1 \rangle$$

$$\textcircled{6} \quad A \cdot A^{-1} = I = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

How to find A^{-1}

$$\begin{bmatrix} 1 & 5 \\ 2 & 7 \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\therefore \begin{bmatrix} 1 & 5 \\ 2 & 7 \end{bmatrix} \begin{bmatrix} a \\ c \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad \text{AND} \quad \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} b \\ d \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 5 & | & 1 & 0 \\ 2 & 7 & | & 0 & 1 \end{bmatrix} \xrightarrow{\text{OR}} \begin{bmatrix} 1 & 0 & | & A^{-1} \\ 0 & 1 & | & A^{-1} \end{bmatrix}$$

Gaussian Elim.

$$\textcircled{\rightarrow} \quad Ax = b$$

Q. When is this solvable?

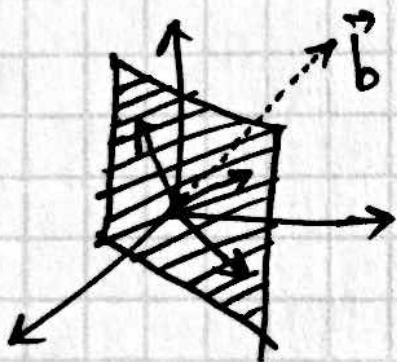
A. When A is invertible.

or A is non-singular,

i.e., $A\hat{x} = 0$ for $\hat{x} \neq 0$



\vec{b} needs to be in the column space of A .



If 3 3D vectors make up 2D space, then any \vec{b} may not fall on that plane.

$\textcircled{\rightarrow}$ 2 3D vectors can be combined to form 3rd 3D vector.

~~Any ways of combining called null space.~~

Some space remains uncovered called A is singular.

This means columns are not indep.

$$\therefore \det(A) = 0$$

⑤ Some basic properties

① $AB \neq BA$ non-Commutative

② $A(BC) = (AB)C$ Associative

③ $(AB)^{-1} = B^{-1}A^{-1}$

④ $(AB)^T = B^T A^T$

⑤ Symmetric matrix when $A^T = A$

⑥ $A^T A$ always symmetric